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Recommended Tools

Picture	Name
SUPPHONE STATE OF THE PROPERTY	Allen Wrench Set
	1/2" Snapring Pliers



What is the WCP Rotation SS Gearbox (2 Stages)?

This gearbox is designed to assist teams in creating rotational arm joints. This was modeled after the 973/1323 arm gearbox from 2011. 1323 used a similar gearbox in 2019 and realized how much work went into creating rotational/arm gearboxes.

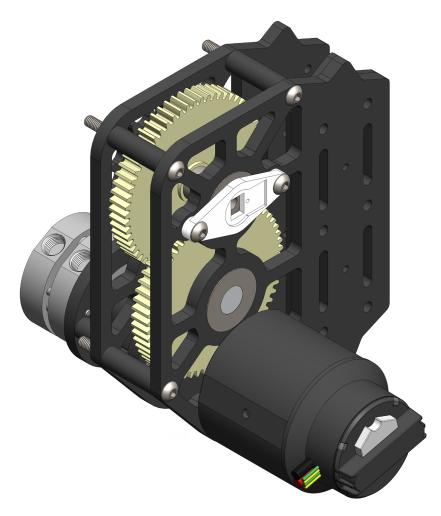
The main features of this gearbox are:

- Native Falcon support
- Compact, 2 stages
- Ability to add a 3rd stage via VersaPlanetary (Can be 1 or more stages)
- Ability to add a 4th stage via Chain Reduction
- Friction Brake Integration
- Clamp to a 1x2" piece of tubing or VersaFrame
- CAM Tensioning
- Built in external Encoder Mount

An application of creating an arm with this gearbox is shown at the end of this manual.



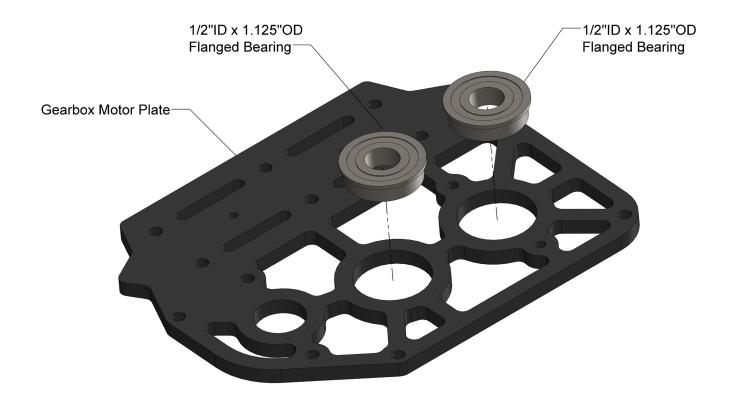
Assembly Instructions





Step 1

Press both bearings into the moto plate. This should be a light press it. The bearing flages should both be on the same side.

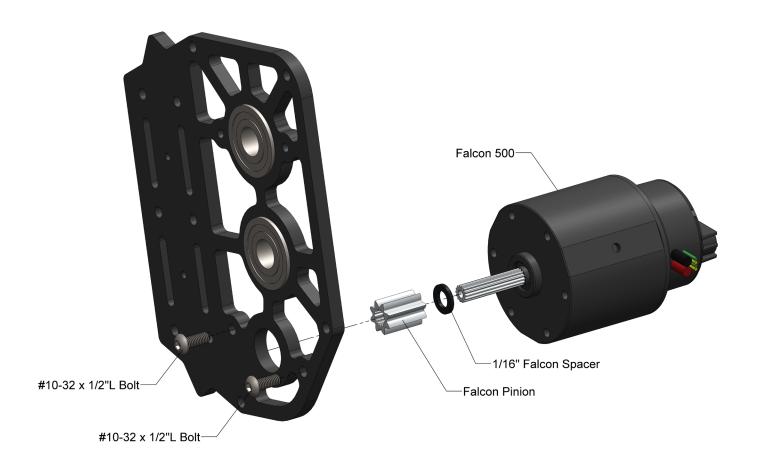




Step 2

Install the Falcon motor with 2 #10-32 x 1/2"L bolts.

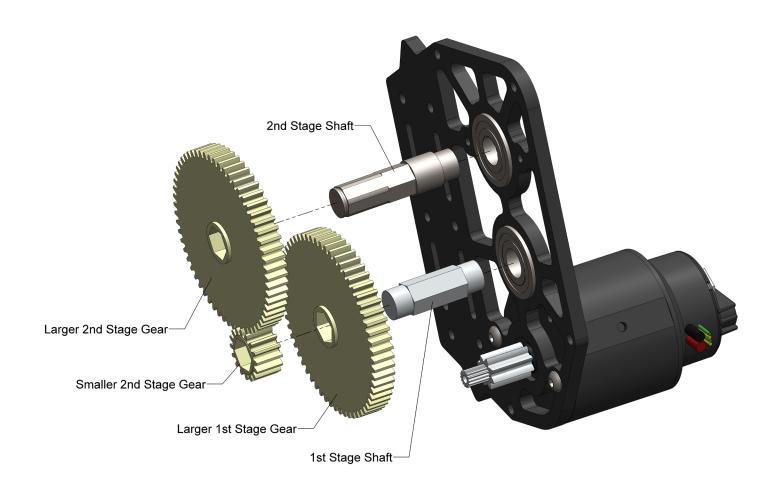
Install the desired pinion and 1/16" Falcon Spacer.





Step 3

Slide all desired gears and shaft into place.

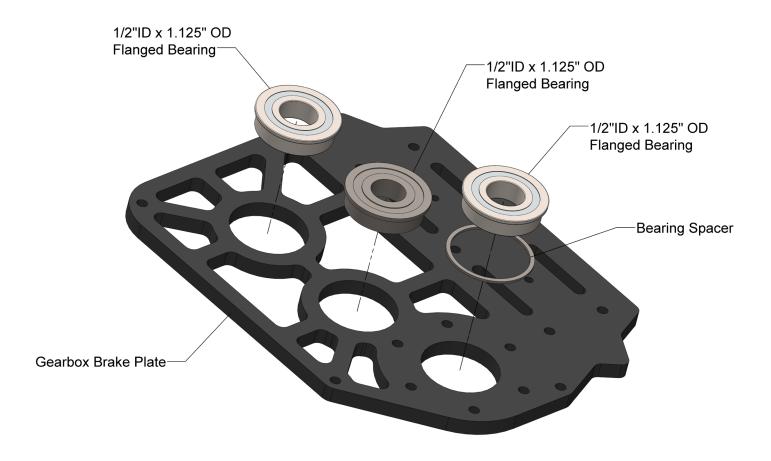




Step 4

Press both bearings into the moto plate. This should be a light press it. The bearing flages should both be on the same side.

The 1/2" bearing that alligns with the brake requires a spacer to be intalled between the plate and flange.

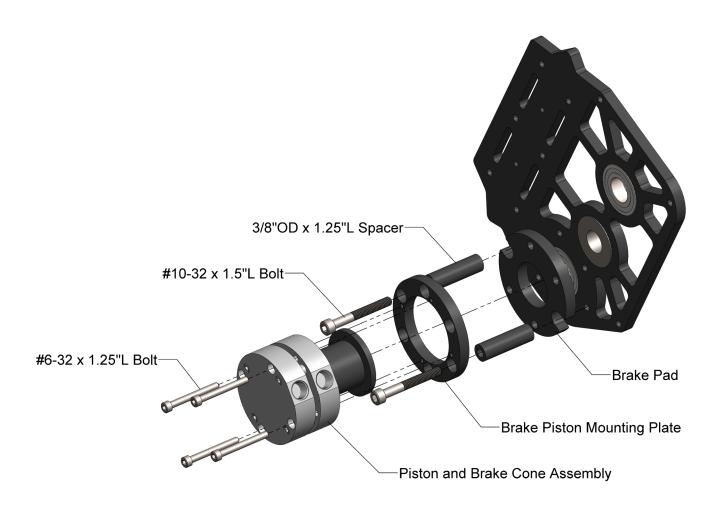




Step 5

Note: This step can be ommitted if the brake was not purchased.

The brake must be assembled in place. For more detailed brake assembly steps, refer the the WCP Friction Brake Manual.

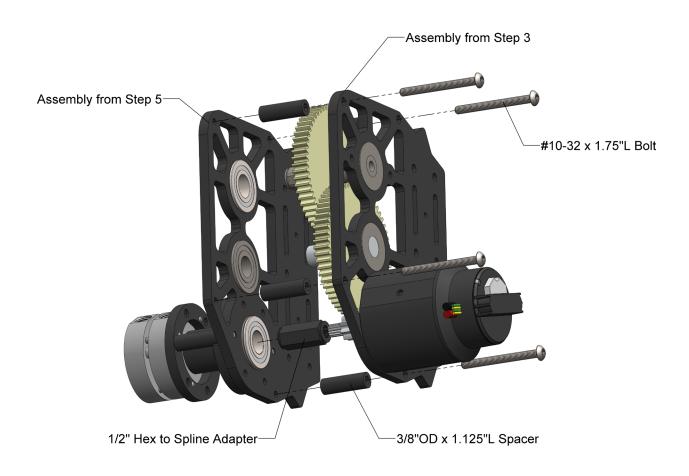




Step 6

Attach the two halves of the gearbox using 4 #10-32 x 1.75"L bolts and 4 1.125"L spacers.

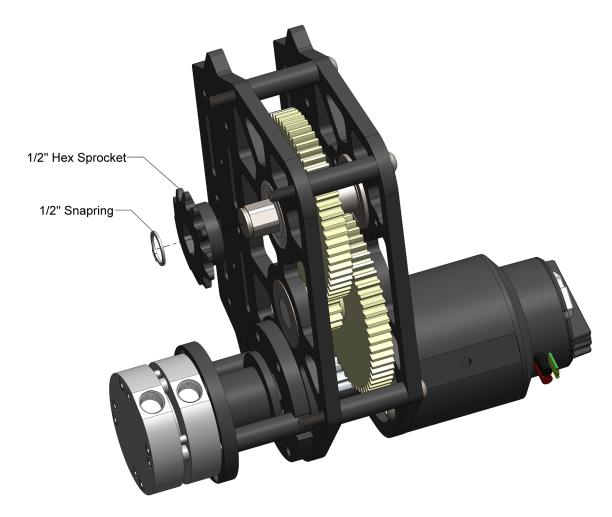
Note: If the brake was not installed in Step 5, the 1/2" Hex to Spline Adapet can be ommitted.





Step 7

Attached desired output sprocket and retain with 1/2" snapring.



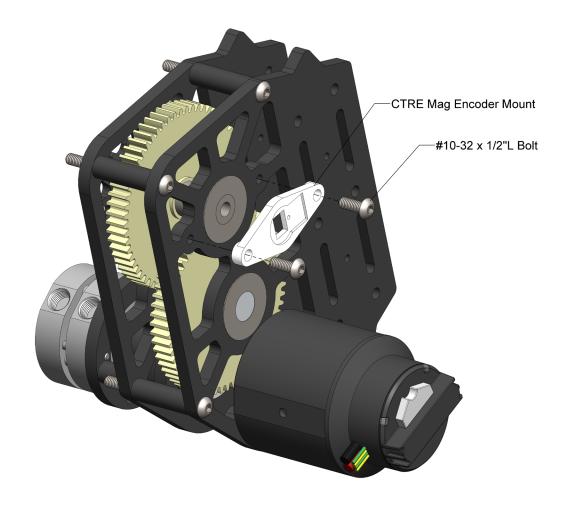


Step 8

Use 2 #10-32 x 1/2"L bolts to attached the Mag Encoder mount.

Note: The CTRE Mag Encoder Mount is not included and may be printed. Teams may choose to design their own mount or use the one in the CAD model. Magnet will come pre-installed in the shaft.

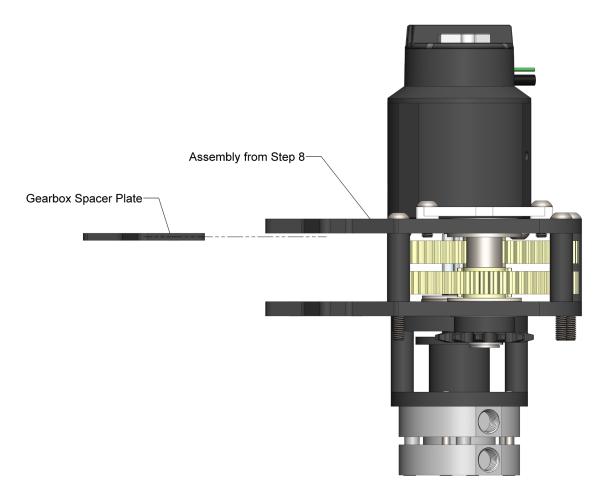
Warning: DO NOT ever tighten bolts and crush 3D printed mount.





Step 9

The gearbox spacer is required for the proper spacing to mount to a 1"x2" tube. Allign the spacer plate with the gearbox plate and use the mounting holes.





Kit Contents

Kit Contents			
Picture	Name	QTY	Kit
	Gearbox Motor Plate	1	Base Kit
	Gearbox Brake Plate	1	Base Kit
	Spacer Plate	1	Base Kit
	1st Stage Shaft	1	Base Kit
	2nd Stage Shaft	1	Base Kit



Picture	Name	QTY	Kit
	1/2" Thunder Hex ID x 1.125"OD Flanged Bearing	1	Base Kit
	1/2"ID x 1.125"OD Flanged Bearing	S	Base Kit
	#10-32 x 1.5"L Bolt	4	Base Kit



Recommended Parts to Buy

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Picture	Name	QTY	
	Falcon Pinion	1	
	Larger 1st Stage Gear	1	
	Smaller 2nd Stage Gear	1	
O REAL PROPERTY OF THE PROPERT	Larger 2nd Stage Gear	1	
	Motor	1	



Picture	Name	QTY
	3/8"OD x 1.125"L Spacer	4
	Friction Brake (1/2" Hex)	1
	1/2" Hex to Spline Adapter	1
	#10-32 x 1/2"L Bolt	2
	1/2" Snapring (WCP-0229)	1



Picture	Name	QTY
	1/2" Hex Bearing	1



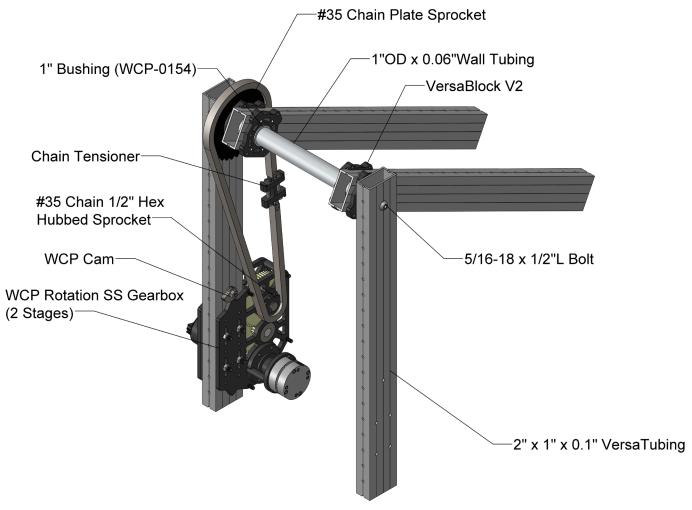
Printable Components

Picture	Name	QTY
	Bearing Spacer	1
	CTRE Mag Encoder Mount	1



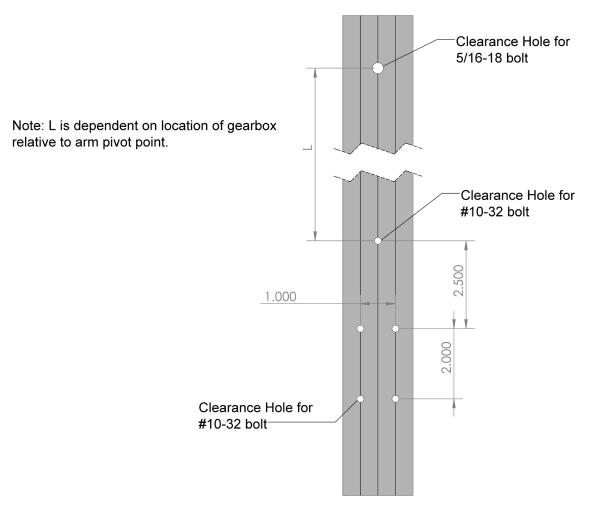
Application Example - Basic Arm

This example utilizes the WCP Rotation SS Gearbox and Versa Blocks for a simple and easy to fabricate arm that teams with limited manufacturing resources can make with basic hand tools.





Mounting Holes





Revision Table

Revision Date	Revision #	Description
1/10/2020	1.1	First revision created.